# e2v

#### CX1191D Deuterium Thyratron

The data to be read in conjunction with the Hydrogen Thyratron Preamble.

#### ABRIDGED DATA

Deuterium-filled tetrode thyratron of ruggedised construction, suitable for general switching applications. It is used for switching peak powers up to 8.0 MW at high repetition rates under a wide range of operating conditions. It has a rugged, internally connected reservoir.

Peak forward anode voltage					35	kV max
Peak anode current					500	A max
Average anode current						
Anode heating factor			8	.0	x 10 <sup>9</sup> V	Apps max
Peak output power					8.0	MW max

#### GENERAL

#### Electrical

Cathode (connected internally

to one end of heater)	oated
Heater voltage 6.3 $\pm$ 7 <sup>1</sup> / <sub>2</sub>	2% V
Heater current 12.5	А
Tube heating time (minimum) (see note 1) . 5.0	min
Inter-electrode capacitances (approximate):	
anode to grid 2 (grid 1 and cathode	
not connected) 9.0	рF
anode to grid 1 (grid 2 and cathode	
not connected) 4.5	рF
anode to cathode (grid 1 and grid 2	
not connected)	рF

#### Mechanical

Overall length		223.8 mm (8.812 inches) max
Overall diameter		. 65.1 mm (2.562 inches) max
Net weight		340 g (12 ounces) approx
Mounting position (see no	te 2) .	any
Base		B4D, bayonet
Торсар		BS448-CT3
Cooling (See note 3)		natural



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#### PULSE MODULATOR SERVICE MAXIMUM AND MINIMUM RATINGS (Absolute values)

	IVIII	n iviax
Anode		
Peak forward anode voltage		
(see note 1)		35 kV
Peak inverse anode voltage		
(see note 4)		10 kV
Peak anode current		500 A
Average anode current		0.5 A
Rate of rise of anode current		
(see note 5)		2500 A/µs
Anode heating factor		8.0 x 10 <sup>9</sup> VApps

N/1:m

Min

Max

Max

#### Grid 2

Unloaded grid 2 drive pulse voltage

(see note 6)	750	V
Grid 2 pulse duration 1.0	-	μs
Rate of rise of grid 2 pulse (see note 5) . 1.0	-	kV/μs
Grid 2 pulse delay 0.5	3.0	) µs
Peak inverse grid 2 voltage	200	V
Loaded grid 2 bias voltage $\ldots -50$	- 120	V
Forward impedance of		
grid 2 drive circuit 100	1000	Ω

#### Grid 1 - DC Primed (See note 7)

DC grid 1 unloaded priming voltage	75	150	V
DC grid 1 priming current	50	100	mΑ

#### Grid 1 - Pulsed

Unloaded grid 1 drive pulse voltage

(see note 6)	300	750 V
Grid 1 pulse duration	. 2.0	- μs
Rate of rise of grid 1 pulse (see note 5)	. 1.0	- kV/μs
Peak inverse grid 1 voltage		200 V
Loaded grid 1 bias voltage		. see note 8
Peak grid 1 drive current	. 0.3	1.0 A

#### Cathode

Heater voltage .						$6.3 \pm 7^{1}/_{2}\%$	V
Tube heating time	see r	note	1)			5.0 -	min

#### Environmental

Ambient	ten	npe	rat	ure				- 55	+90	°C
Altitude								. –	3	km
								-	10 000	ft

#### **CHARACTERISTICS**

M	in Typical	Max
Critical DC anode voltage for		
conduction (see note 9)	0.3	1.0 kV
Anode delay time		
(see notes 9 and 10)	0.15	0.25 μs
Anode delay time drift		
(see notes 9, 11 and 12)	20	50 ns
Time jitter (see notes 9 and 12)	1.0	5.0 ns
Heater current (at 6.3 V) 11	12.5	13 A

## RATINGS FOR SINGLE-SHOT OR CROWBAR SERVICE (See note 7)

DC forward anode voltage (see note 1) 35	kV max
Peak anode current 5000	A max
Product of peak current and	
pulse duration 0.2	A.s max
Repetition frequency 1 pulse per	10 s max

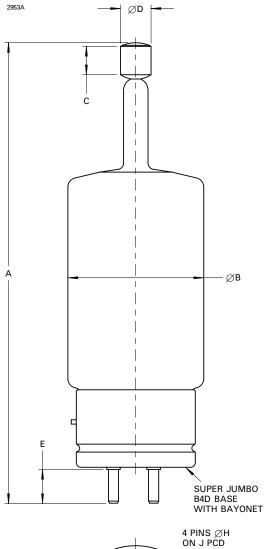
#### NOTES

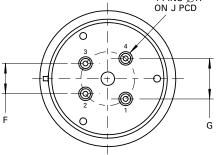
1. The maximum permissible peak forward voltage for instantaneous starting is 20 kV and there must be no overshoot.

For single-shot and crowbar applications, each tube is tested to withstand 35 kV DC at 6.3 V heater voltage for 10 minutes, with 100 mA grid 1 drive current and -100 V grid 2 bias.

- 2. Clamping is only permissible by the base.
- 3. In some applications, air cooling may be necessary to prevent the base temperature from exceeding 200 °C.
- 4. The peak inverse voltage must not exceed 25 kV for the first 25  $\mu s$  after the anode pulse.
- 5. The rate of rise refers to that part of the leading edge of the pulse between 25% and 75% of the pulse amplitude.
- 6. Measured with respect to cathode. In certain cases the maximum drive pulse voltage may be exceeded without damage to the tube; a maximum value of 2.5 kV is then recommended. When grid 1 is pulse driven, the last 0.25  $\mu s$  of the top of the grid 1 pulse must overlap the corresponding first 0.25  $\mu s$  of the top of the delayed grid 2 pulse.
- When DC priming is used on grid 1, a negative bias of 100 to 200 V must be applied to grid 2 to ensure anode voltage hold-off. DC priming is recommended for pulse modulator and crowbar service.
- 8. DC negative bias voltages must not be applied to grid 1. When grid 1 is pulse driven, the potential of grid 1 may vary between -10 and +5 V with respect to cathode potential during the period between the completion of recovery and the commencement of the succeeding grid pulse.
- Typical figures are obtained on test using conditions of minimum grid drive. Improved performance can be expected by increasing the grid drive.
- 10. The time interval between the instant at which the rising unloaded grid 2 pulse reaches 25% of its pulse amplitude and the instant when anode conduction takes place.
- 11. The drift in delay time over a period from 10 seconds to 10 minutes after reaching full voltage.
- 12. For equipment where jitter and anode delay time drift are not important, the tube may be triggered by applying a single pulse to grid 2 and connecting grid 1 to grid 2 via a 1000 pF capacitor shunted by a 0.1 M $\Omega$  resistor.

#### OUTLINE (All dimensions without limits are nominal)





Ref	Millimetres	Inches
A	217.5 ± 6.4	8.562 ± 0.250
В	65.08 max	2.562 max
С	12.7 min	0.500 min
D	14.38 ± 0.18	0.566 ± 0.007
Е	15.88	0.625
F	14.28	0.562
G	19.05	0.750
Н	4.750 ± 0.076	0.187 ± 0.003
J	25.4	1.000

Inch dimensions have been derived from millimetres.

Pin	Element
1	Grid 1
2	Heater, cathode
3	Heater
4	Grid 2
Тор сар	Anode

#### HEALTH AND SAFETY HAZARDS

e2v technologies hydrogen thyratrons are safe to handle and operate, provided that the relevant precautions stated herein are observed. e2v technologies does not accept responsibility for damage or injury resulting from the use of electronic devices it produces. Equipment manufacturers and users must ensure that adequate precautions are taken. Appropriate warning labels and notices must be provided on equipments incorporating e2v technologies devices and in operating manuals.

## 🖄 High Voltage

Equipment must be designed so that personnel cannot come into contact with high voltage circuits. All high voltage circuits and terminals must be enclosed and fail-safe interlock switches must be fitted to disconnect the primary power supply and discharge all high voltage capacitors and other stored charges before allowing access. Interlock switches must not be bypassed to allow operation with access doors open.

### X-Ray Radiation

All high voltage devices produce X-rays during operation and may require shielding. The X-ray radiation from hydrogen thyratrons is usually reduced to a safe level by enclosing the equipment or shielding the thyratron with at least 1.6 mm ( $^{1}/_{16}$  inch) thick steel panels.

Users and equipment manufacturers must check the radiation level under their maximum operating conditions.

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